

Performance analysis of the Early-Est software within the tsunami early warning system installed at the INGV



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Abstract

Fast, accurate and reliable earthquake source parameters are crucial for seismologically based tsunami early warning procedures. These parameters should be obtained within a few minutes after event origin time when coastlines in the near-field of the seismic source are potentially threatened. Thus there is no time for a detailed analysis and accurate revision of the automatic solution, and only a quick validation/rejection of the results may be performed in most of the cases by a seismologist. Within this context it is important to have a reliable estimate of the uncertainties of the earthquake epicenter location, depth and magnitude. Early-Est (EE) is a software currently installed at the recently established Centro Allerta Tsunami (CAT) the operational segment of the Italian National Tsunami Warning Centre (It-NTWC), in the seismic monitoring centre of the Istituto Nazionale di Geofisica e Vulcanologia (INGV) in Rome (Italy). EE operates on continuous-realtime seismic waveform data to perform trace processing and picking, phase association, event detection, hypocenter location, and event characterization. This characterization includes mb and Mwp magnitudes, and the determination of duration, T0, large earthquake magnitude, Mwpd, and assessment of tsunamigenic potential using Td and T50Ex. In order to test the performance of the fully automatic EE solutions for tsunami early warning, we first compare the hypocenters and magnitudes provided at globa scale by different agencies (NEIC, GFZ, CSEM) for events with magnitude Mw ≥ 5.5. We then compare the empirical uncertainties we obtain in this way with EE solution and with the differences between the EE system and the reference catalogues. Our analysis shows that EE is suitable for the purpose of the CAT since it generally provides fully automatic reliable locations and magnitudes within the uncertainties expected from statistical analysis of the manually revised reference catalogs We also analyze the performances of EE for several offshore earthquakes occurred in the last two years in the Mediterranean and analyze the warning messages that would have been issued for each of the events considered.

 $u = 16.5 \pm 24$

Empirical uncertainty of epicenter location and magnitude

The Early-Est (EE) software is running at INGV continuously since begin of march 2012. Early-Est is a software for global automatic location and assessment of tsunamigenic potential (Lomax and Michelini 2009a, 2009b, 2011). Once EE has first located an earthquake, continuously re-locate the event by adding new phases and re-computing the magnitudes (mb, Mwp and Mwpd). Relocation is updated every minute during the hour after event origin time.

In this work we evaluated the empirical uncertainties of epicenter location and magnitude for earthquakes with magnitude larger than M ≥ 5.5 at global scale provided by EE. The epicenter locations and magnitude differences between the GFZ, the EMSC and the NEIC catalogues are used to set empirical uncertainties. Magnitudes values and magnitudes types may vary; for this reason we set the threshold for the minimum magnitude for the data request at M≥5.0. Using this threshold level, we ensure to have selected all earthquakes with magnitude M≥ 5.5. The time windows for data selection starts for the NEIC at begin 2004, for the EMSC at October 2004 and for GFZ at august 2006. The time window ends at end 2013 for all cataloos. The derived empirical uncertainties are then used to set the reliability of the fully automatic locations and magnitude estimations provided by EE.

EE runs fully automatic and no revision is performed on the derived earthquake parameters. The three reference catalogs are manually revised

Figure 1 Comparison of the epicenter location differences in km for magnitudes ranges (see table at the bottom of this box for color ranges) between the three reference catalogs The mean μ and the standard deviation are computed for the entire magnitude range dataset

Figure 2

Comparison of the epicenter location differences in km for magnitudes ranges between the three reference catalogs and FF. The distribution is wider and the mean difference is about 10 km larger than in figure 1. Such differences are generally not relevant for offshore tsunamigenic large events

Figure 3

The GFZ catalog did not

with NFIC magnitudes.

provided the magnitude type.

Thus we compared only FMSC



EE provids three type of magnitudes: mb, Mwp and Mwpd. The magnitude mb is always computed, while Mwp and Mwpd only for the larger events. Only the magnitude type which compares with the one listed into the two reference catalogs is used to produce the following histograms and to compute the mean and the standard deviation



Rapid focal mechanism determination

The use of P first-motion data is critical in Ealry-est for determining focal mechanisms in the first 5-10min after an event since waveform mechanisms are only available 10-20min or later after origin time. The program fmamp is a probabilistic global-search, focal mechanism code using first-motion polarities (fmamp polarity), or high-frequency average P amplitudes (fmamp amp aref; Early-est "aref" amplitude measure), or displacement amplitudes derived from the Early-est Mwp magnitude (fmamp amp Mwp). The sign of the amplitude is set from first-motion polarities or a waveform polarity based on the Early-est Mwp measure (Lomax and Michelini, 2012). Predicted radiation amplitudes are calculated using Aki and Richards, 1980, eqs. 4.84-4.86.

Global-search: fmamp uses an oct-tree search (Lomax et al., 2009), which provide a smoother and more complete search and set of "acceptable" solutions than regular grid searches; the set of "acceptable" solutions indicates the uncertainty and quality of the determined mechanisms.

Misfit functions: The fmamp polarity misfit uses a count of agreement between observed and predicted first-motion polarities for each tested fault-plane solution. This misfit function is similar to that of standard first-motioncodes, suchas HASH (Hardebeck and Shearer, 2002). The fmamp amp misfit uses the quality of fit of observed versus predicted P amplitudes to a line through the origin with fixed slope A_obs_mean/A_pred_mean - the expected relation between perfect data and predicted amplitudes. The mean amplitude ratio A_obs_mean/A_pred_mean is related to the event size; this ratio is calculated directly from the observed and predicted data. The amplitude misfit function uses an L1 norm for robustness with regards to amplitude anomalies errors.

Figure 5

Example: Figure 5 shows fmamp and HASH mechanisms for data available at 8 min after origin time for a recent, large Mediterranean earthquake. The fmamp polarity and HASH results are based on the same polarity data and similar misfi function and thus are directly comparable. Note the generally better constraint (less scatter in acceptable P and T axes, and fault planes) and same or higher quality solutions (A, B, C, ...) for the fmamp results relative to HASH. The fmamp amp results, despite having the fewest data, show better agreement with waveform solutions than the other algorithms.

In general, the fmamp polarity and HASH results are often similar, except for quality levels, while the fmamp amplitude solutions, when available, often show higher constraint and quality than the polarity methods. We will investigate using in Comparison of the focal mechanism solutions obtained Early-est: 1) fmamp polarity, giving a small gain in constraint for the Mw=6.2 Greece earthquake obtained

and quality of mechanisms, along with 2) fmamp amp Mwp to automatically 8 minutes after origin time, using fmamp provide additional information and better constrained, higher and HASH compared with the USGS and the global CMT quality mechanisms for moderate and larger events solutions



Towards the pre-operational phase of INGV as candidate Tsunami Watch Provider (cTWP) for the NEAM region (see also poster B227 this session

Between march 2012 and end of december 2013 EE located 5 offshore earthquake with M ≥ 5.5 in the Mediterranean area (Table 1). Based on the location, magnitude and the NEAM decision matrix (Figure 8), the Centro Allerta Tsunami (CAT) at the INGV compiled test tsunami warning messages and tsunami travel times were calculated. Figure 9 and 10 are examples of the message and of the respective tsunami travel time map. The message and the map are automatically generated. These messages are not reviewed by a seismologist and they are not yet disseminated.

1 2012-04-10 12744115 36.36 20.49 19.7 5.7 6.1 6.9 36.23 20.1 19.7 6.1 6.2 6.5 167 20.1 19.7 6.1 6.2 6.5 167 20.1 19.7 6.1 6.2 6.5 167 20.1 19.7 6.1 6.2 6.5 167 20.1 19.7 6.1 19.7 19.7 19.7 19.7 19.7 19.7 19.7 19	łz	date	time	lat	lon	2	nb	nvp mvpd	lat	lon	2	nb	mp	mepd	zec.	lat	1	26
2 2012-09-12 03127143 34.77 24.60 10.0 5.7 5.4 6.2 35.66 24.00 10.0 5.8 5.6 5.9 201 34.74 24. 3 2013-01-08 14116109 39.62 25.49 10.1 5.7 5.7 5.8 39.64 25.59 19.8 6.1 6.0 0.0 174 39.66 25. 4 2013-01-12 131134 55 52 33 0.1 5.5 56.6 6.8 55 19.1 0.5 5.6 5.7 2 104 55 55 19.1 0.5 55 55 10.0 105 55 55 55 55 55 55 55 55 55 55 55 55 5	1	2012-06-10	12:44:15	36.36	28.93	19.7	5.7	6.1 6.9	36.33	29.01	19.7	6.3	6.2	6.5	167	36.36	28.	93
4 2013-10-12 13-13-53 25 22 3 30 31 5 6 3 6 6 6 8 35 39 23 20 85 4 6 3 6 6 7 2 394 35 56 23	2	2012-09-12 2013-01-08	03:27:43	34.77	24.00	10.0	5.7	5.4 6.2	25.06	24.00	10.0	5.0	5.6	5.9	201	24.74	24.	03 54
	4	2013-10-12	13:11:51	35.52	23.30	11.5	6.3	6.6 6.0	35.39	23.20	85.4	6.3	6.6	7.2	194	35.56	23.3	1

List of the 5 offshore events occurred in the NEAM region with $M \ge 5.5$ between the beginning of 2012 and the end 2013. For each event are listed the epicentral coordinates, depth and magnitudes of the last EE iteration (sub table left); the same values corresponding to the first stable solution and the seconds after origin time when these parameters were available (sub table center); and the reference values listed into the EMSC catalog (sub table right).



Figure 10 Tsunami travel times computed for the December 2013 earthquake (Table 1) Triangles with dots are 'virtual' forecast points for which the estimated tsunami arrival times are listed into the alert message (figure 9) Actual forecast points will be used in the pre-operational phase when IOC Member States will subscribe the cTWP services

Conclusions

in table 1).

We compared alobal earthauake cataloas to set empirical uncertainties for the epicenter location and magnitude. For earthauakes with $M \ge 5.5$ the location uncertainty is less than 20 km with a standard deviation smaller than 30 km. Maanitudes between EMSC and NEIC catalogs are coherent and show a standard deviation of 0.1 magnitude; generally differences do not exceed 0.2 magnitude.

Early-Est is running since two year providing automatic earthquake locations at global scale. Our analysis shows that the automatic locations of FF for earthquakes with $M \ge 5.5$ is reliable.

Magnitude estimations compared with the reference catalogs show a mean over estimation of less than 0.1 maanitude with a standard deviation smaller than 0.3 magnitude: differences are decrease for events with $M \ge 6.0$.

Early-Est provides stable and reliable epicenter locations and magnitude estimations, generally within 3-6 minutes after event origin time.

We will further test fast and automatic focal mechanism estimation using fmamp polarity and fmamp amp Mwp. The performed test indicates that reliable focal mechanism solutions can be obtained within 8 minutes from event origin time